

Stochastic Rank Aggregation

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1. RANK AGGREGATION PROBLEM

- Crucial to many applications
 - meta search, collaborative filtering
- Formalization of Two common scenario
 - Unsupervised Rank Aggregation
 Given τ_1, \dots, τ_m , we are to find a consensus ranking π that

$$\max \sum_{i=1}^m \mathcal{M}(\pi, \tau_i),$$

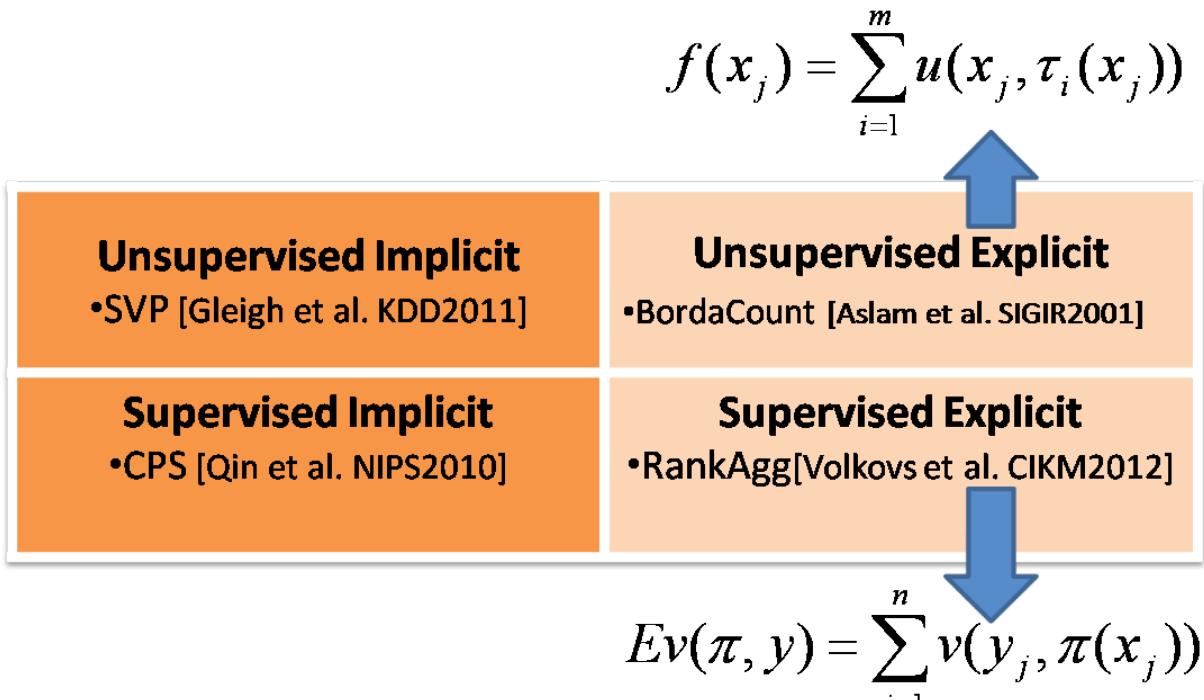
where \mathcal{M} is the similarity measure between two rankings.

- Supervised Rank Aggregation
 Given $\{D^{(i)}\}_{i=1}^N$, and all ranking inputs $\tau_1^{(i)}, \dots, \tau_m^{(i)}$ over $D^{(i)}$, $y^{(i)}$ is the ground truth ranking over $D^{(i)}$, an aggregation function f can be learned by

$$\max \sum_{i=1}^N \mathcal{M}(y^{(i)}, f(\tau_1^{(i)}, \dots, \tau_m^{(i)})).$$

Implicit and Explicit Methods

whether rank information is used directly:

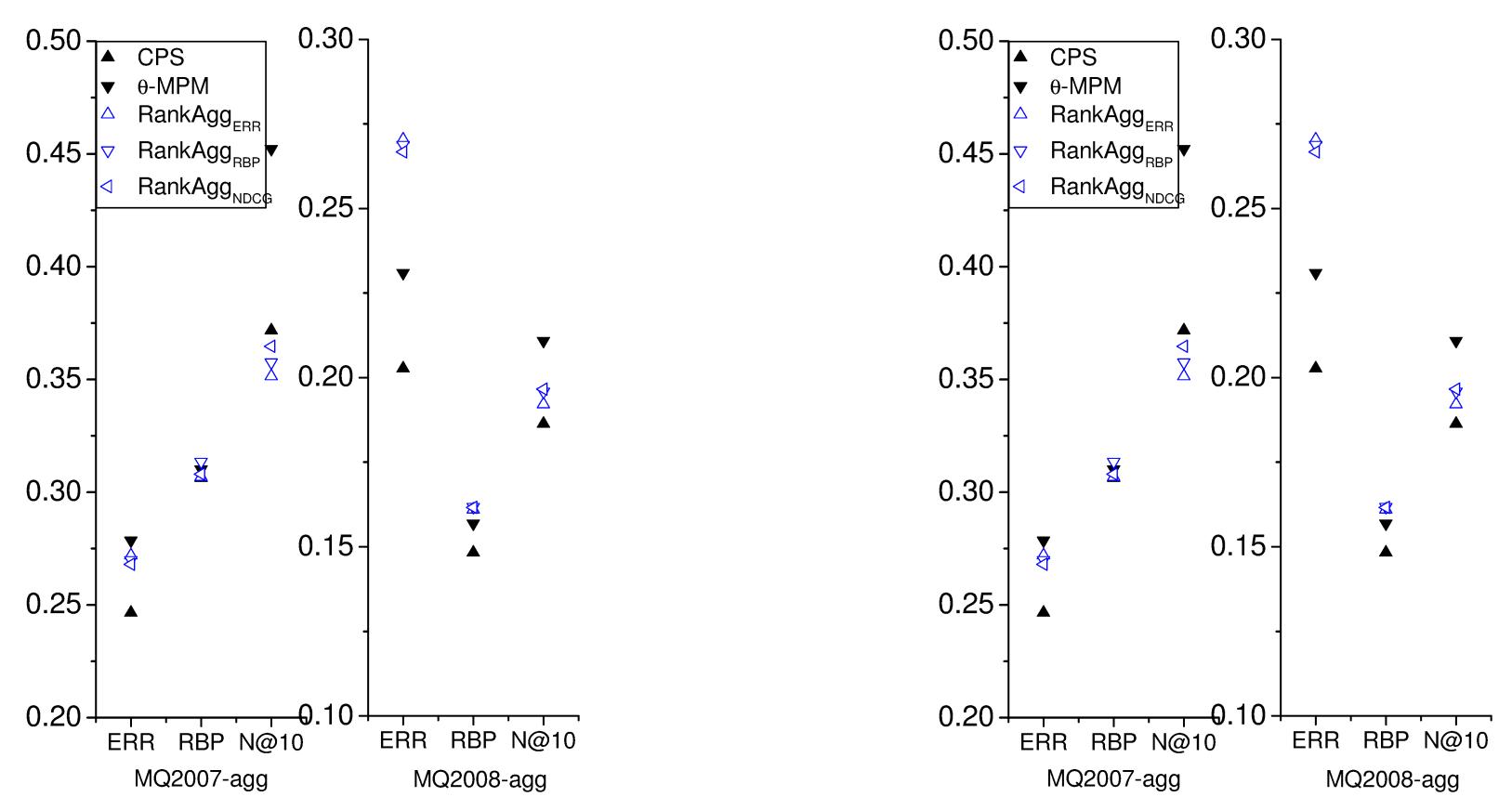


$$f(x_j) = \sum_{i=1}^m u(x_j, \tau_i(x_j))$$

$$Ev(\pi, y) = \sum_{j=1}^n v(y_j, \pi(x_j))$$

2. MOTIVATION

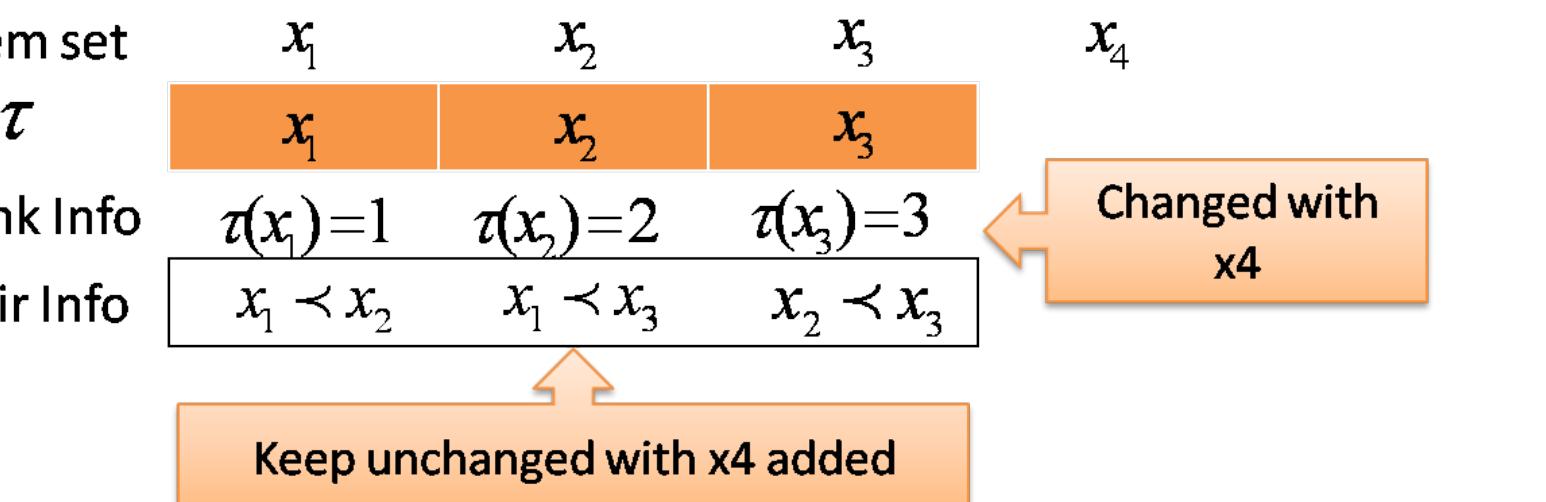
Failure of Explicit Methods:



Underlying Reason: Unreliable rank information from partial rankings

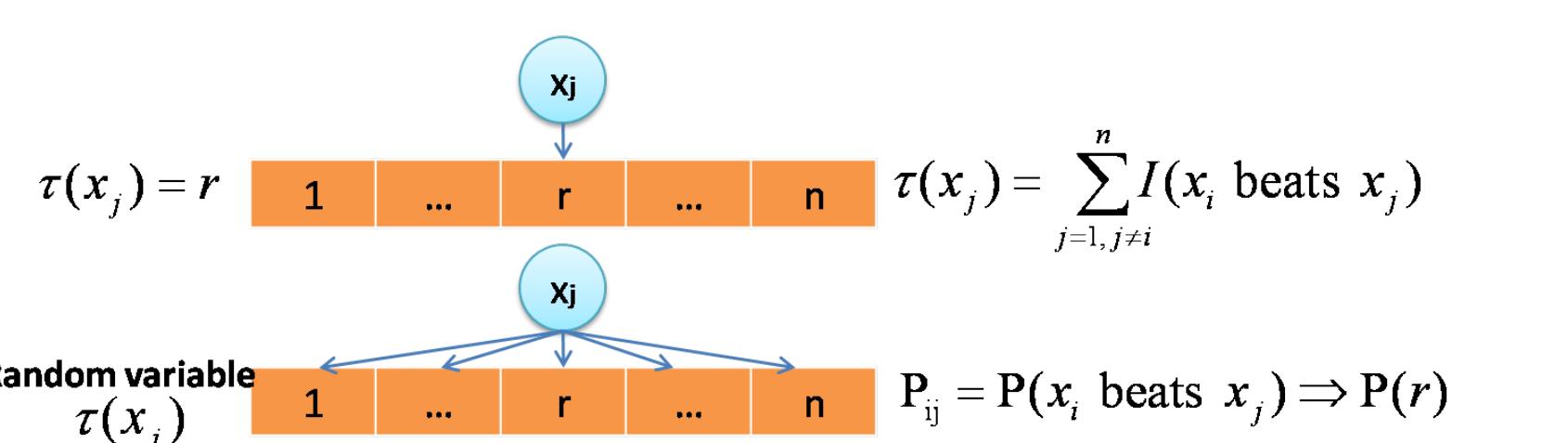
3. STOCHASTIC RANK AGGREGATION

Our Observation: pairwise information is more robust to incompleteness.



Our Solution: Incorporate uncertainty into rank aggregation in a pairwise way

Rank to Rank Distribution



When the new item x_i comes, the rank distribution of x_j , $P(r)$ can be updated as:

$$P^{(t)}(r) = P^{(t-1)}(r-1)P_{ij} + P^{(t-1)}(r)(1 - P_{ij})$$

Stochastic Rank Aggregation (St.Agg) in Unsupervised Scenario

Definition of P_{ij} :

- Encode rank difference information
- e.g.

$$P_{ij} = \begin{cases} \frac{\tau(x_j) - \tau(x_i)}{n}, & \text{if } \tau(x_i) < \tau(x_j) \\ 1 - \frac{\tau(x_i) - \tau(x_j)}{n}, & \text{if } \tau(x_j) < \tau(x_i) \\ 0.5, & \text{otherwise} \end{cases}$$

Expectation: New Ranking Function

$$f_s(x_j) = \sum_{i=1}^m \sum_{r=1}^n u(x_j, \tau_i(x_j)) P(r)$$

Stochastic Rank Aggregation (St.Agg) in Supervised Scenario

Definition of P_{ij} :

- assume $s_j \sim \mathcal{N}(f(x_j), \sigma^2) \Rightarrow s_i - s_j \sim \mathcal{N}(f(x_i) - f(x_j), 2\sigma^2) \Rightarrow P_{ij} = P(s_i - s_j > 0)$

Expectation:

- New Optimization Objective Functions, e.g.

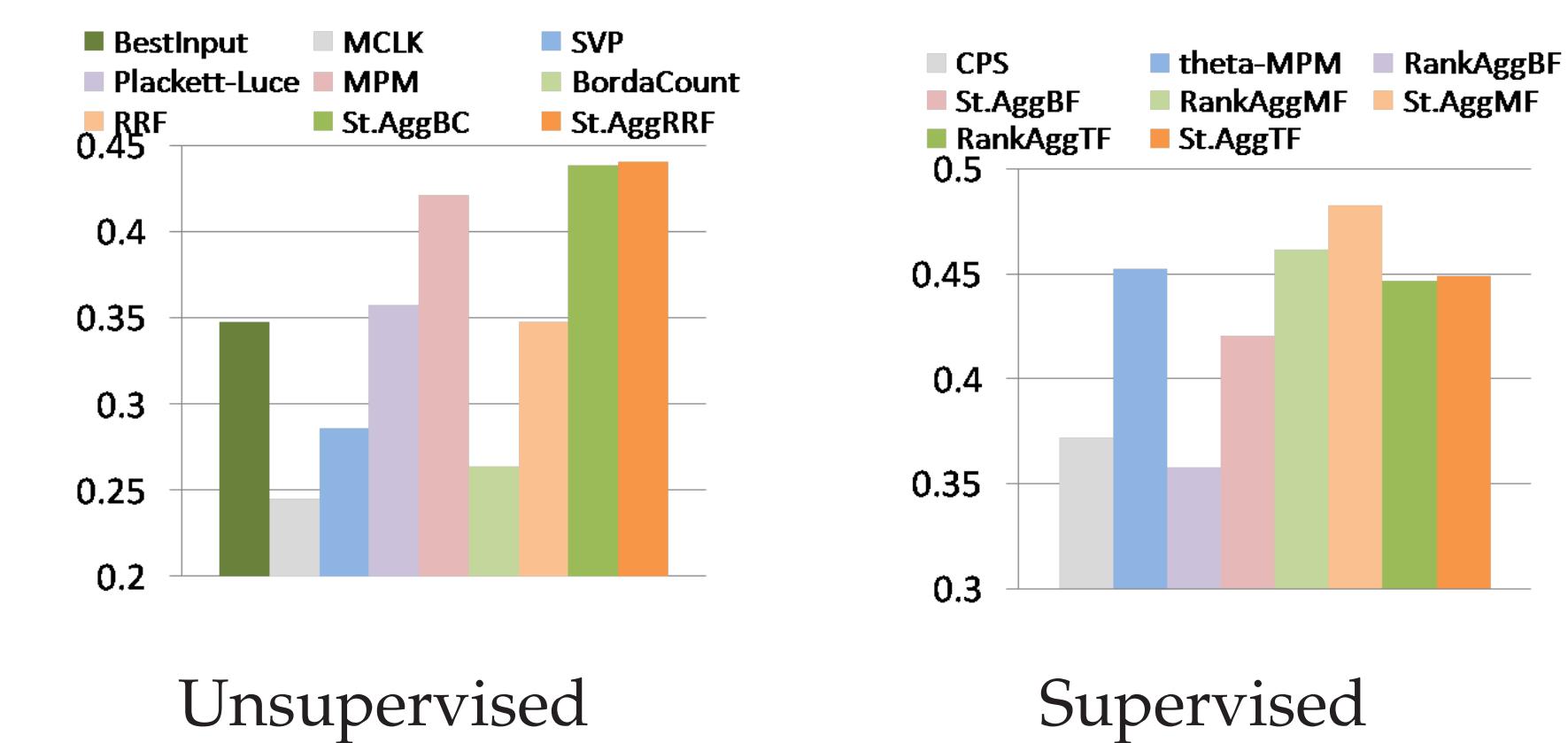
$$Ev_s(\pi, y) = \sum_{j=1}^n \sum_{r=1}^n v(y_j, r) P_j(r)$$

Feature-based optimization framework

- Feature Mapping Design: (1) item Ψ_{BF} ; (2) item-item Ψ_{MF} ; (3) user-item-item Ψ_{TF} ;
- Learning Method: Gradient Method

4. EXPERIMENTS

- Datasets: metasearch tasks in LETOR4.0
 - e.g. MQ2007-agg and MQ2008-agg
- Effectiveness: e.g. NDCG@10 on MQ2007-agg

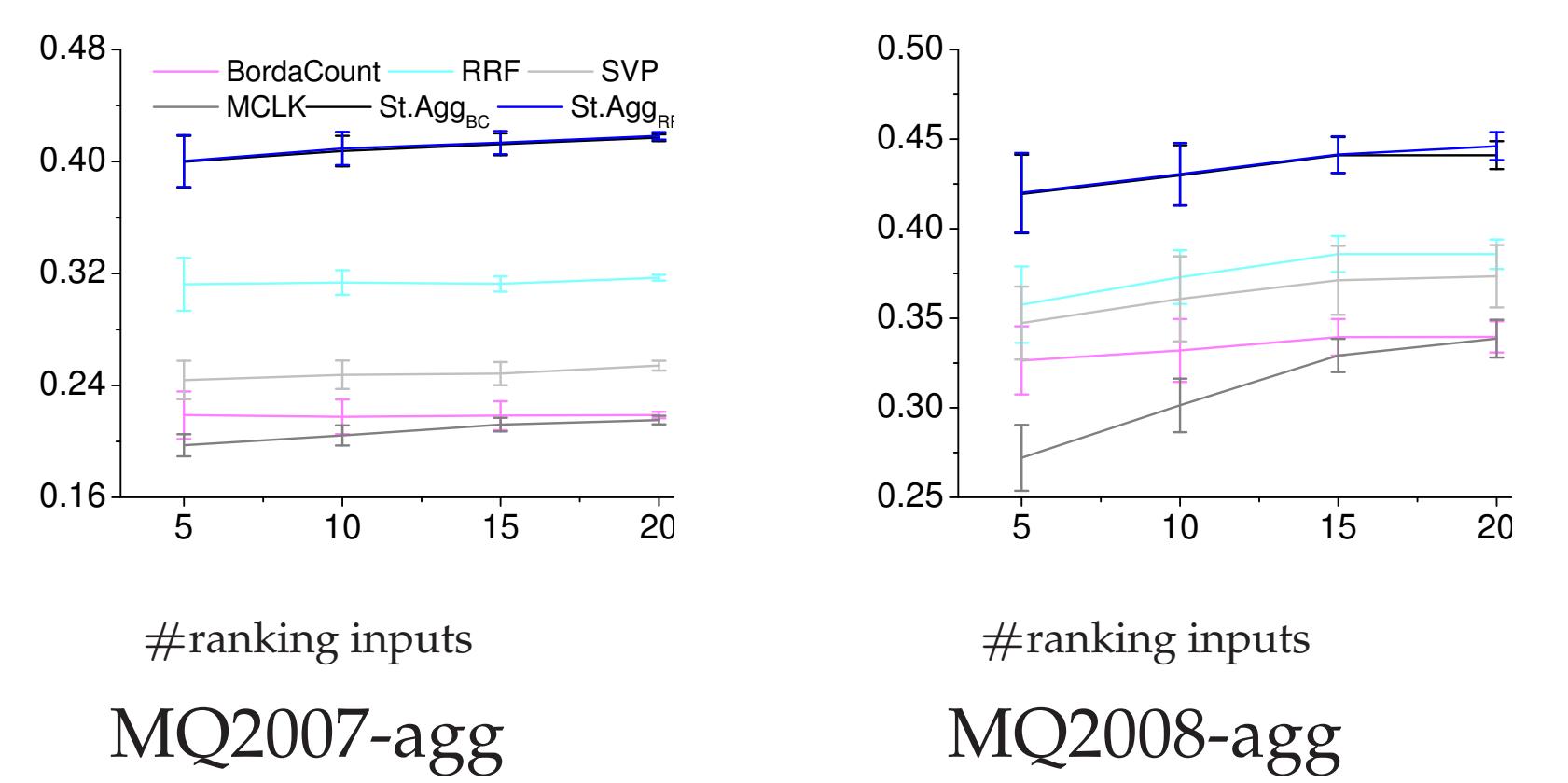


Unsupervised

Supervised

- St.Agg performs better than baselines in both scenarios;
- The item-item feature Ψ_{MF} performs best in supervised scenario.

Robustness: e.g. NDCG@5 of St.Agg



MQ2007-agg

MQ2008-agg

St.Agg stays above baselines however the ranking inputs change.

5. CONCLUSION & FUTURE WORK

Conclusion:

- We find that unreliable rank information from partial ranking inputs will make the approaches directly using rank information fail in practice;
- We propose a novel rank aggregation framework by incorporating uncertainty to tackle this problem;
- The framework turns out to be effective and robust.

Future work:

- To find better ways to define rank distributions;
- To utilize this stochastic rank aggregation framework in other applications.